

# ChE 400: Numerical Differentiation and Integration (H-6)

Gerardine G. Botte

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## Objectives

- **General:**
  - Apply the concepts of this chapter for the solution of chemical engineering problems that require the calculation of integrals and derivatives numerically
- **Specific objectives:**
  - Use the backward, forward, and central approximations to calculate derivatives numerically
  - Use the trapezoidal rule for integration
  - Use Simpson's rule for integration
  - Use Excel and Matlab to calculate derivatives and integrals numerically

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## Outline

Numerical  
Differentiation  
– Overview  
– Discretization of a  
function  
– Examples  
Numerical  
Integration  
– Overview  
– Trapezoidal rule  
– 1/3 Simpson's  
rule  
Lab Practice  
– Use of Excel  
– Use of Matlab

- **Numerical Differentiation**
  - Overview
  - Discretization of a function
  - Examples
- **Numerical Integration**
  - Overview
  - Trapezoidal rule
  - 1/3 Simpson's rule
- **Lab Practice**
  - Use of Excel
  - Use of Matlab

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<p><b>Numerical Differentiation</b></p> <ul style="list-style-type: none"> <li>- Overview</li> <li>- Discretization of a function</li> <li>- Examples</li> </ul> <p><b>Numerical Integration</b></p> <ul style="list-style-type: none"> <li>- Overview</li> <li>- Trapezoidal rule</li> <li>- 1/3 Simpson's rule</li> </ul> <p><b>Lab Practice</b></p> <ul style="list-style-type: none"> <li>- Use of Excel</li> <li>- Use of Matlab</li> </ul>	<h2>Numerical Differentiation</h2> <hr/> <ul style="list-style-type: none"> <li>• Sometimes the function is very complex and the derivative of the function can't be evaluated analytically</li> <li>• Need to use numerical methods</li> <li>• Numerical differentiation methods are based on Taylor's series expansion</li> <li>• Their accuracy depends on the number of terms involved in the calculation of the derivative and the profile of the function             <ul style="list-style-type: none"> <li>- Usually the more terms used in the series the better the accuracy</li> <li>- The final accuracy of the computation is strongly affected by the profile of the function</li> </ul> </li> </ul> <p style="text-align: right;">CHE 400      9/6/2006      4</p>
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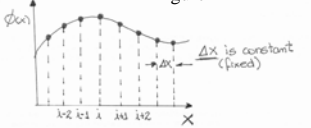
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<p><b>Numerical Differentiation</b></p> <ul style="list-style-type: none"> <li>- Overview</li> <li>- Discretization of a function</li> <li>- Examples</li> </ul> <p><b>Numerical Integration</b></p> <ul style="list-style-type: none"> <li>- Overview</li> <li>- Trapezoidal rule</li> <li>- 1/3 Simpson's rule</li> </ul> <p><b>Lab Practice</b></p> <ul style="list-style-type: none"> <li>- Use of Excel</li> <li>- Use of Matlab</li> </ul>	<h2>Discretization of a Function</h2> <hr/> <ul style="list-style-type: none"> <li>• The first step to apply numerical differentiation is to discretize the continuous function into discrete points, as shown in the figure</li> </ul> <p style="text-align: center;">Figure 1</p>  <p style="text-align: right;">5</p>
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<p><b>Numerical Differentiation</b></p> <ul style="list-style-type: none"> <li>- Overview</li> <li>- Discretization of a function</li> <li>- Examples</li> </ul> <p><b>Numerical Integration</b></p> <ul style="list-style-type: none"> <li>- Overview</li> <li>- Trapezoidal rule</li> <li>- 1/3 Simpson's rule</li> </ul> <p><b>Lab Practice</b></p> <ul style="list-style-type: none"> <li>- Use of Excel</li> <li>- Use of Matlab</li> </ul>	<h2>Taylor's Series</h2> <hr/> <ul style="list-style-type: none"> <li>• Using Taylor's series expansion for the points <math>\phi_{i+1}</math>, <math>\phi_{i+2}</math>, <math>\phi_{i-1}</math>, <math>\phi_{i-2}</math></li> </ul> $\phi_{i+1} = \phi_i + (\Delta x) \phi_i' + \frac{(\Delta x)^2}{2!} \phi_i'' + \frac{(\Delta x)^3}{3!} \phi_i''' + \frac{(\Delta x)^4}{4!} \phi_i^{IV} + \dots + (1)$ $\phi_{i+2} = \phi_i + 2(\Delta x) \phi_i' + \frac{(2\Delta x)^2}{2!} \phi_i'' + \frac{(2\Delta x)^3}{3!} \phi_i''' + \frac{(2\Delta x)^4}{4!} \phi_i^{IV} + \dots + (2)$ $\phi_{i-1} = \phi_i - (\Delta x) \phi_i' + \frac{(-\Delta x)^2}{2!} \phi_i'' - \frac{(\Delta x)^3}{3!} \phi_i''' + \frac{(-\Delta x)^4}{4!} \phi_i^{IV} + \dots + (3)$ $\phi_{i-2} = \phi_i - 2(\Delta x) \phi_i' + \frac{(-2\Delta x)^2}{2!} \phi_i'' - \frac{(2\Delta x)^3}{3!} \phi_i''' + \frac{(-2\Delta x)^4}{4!} \phi_i^{IV} + \dots + (4)$ <p style="text-align: right;">6</p>
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## Numerical Approximations

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**Numerical Differentiation**

- Overview
- Discretization of a function
- Examples

**Numerical Integration**

- Overview
- Trapezoidal rule
- 1/3 Simpson's rule

**Lab Practice**

- Use of Excel
- Use of Matlab

- Using a combination of equations (1) to (4) the expressions for the numerical derivatives can be obtained
- The approximations are named in accordance with the points used, e.g.,:
  - Backward approximations (uses backward points in the calculation)
  - Forward approximation (uses forward points)
  - Central approximation (uses central points)

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## Backward Approximation First Derivative ( $\phi_1'$ )

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**Numerical Differentiation**


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**Lab Practice**

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- Use of Matlab



- Rearranging Eq. 3 to obtain the first derivative at node point i:

$$(\Delta x)\phi_1' = \phi_1 - \phi_{i-1} + \frac{(-\Delta x)^2}{2!} \phi_1'' - \frac{(\Delta x)^3}{3!} \phi_1''' + \frac{(-\Delta x)^4}{4!} \phi_1^{IV} + \dots + (3.1)$$

- Dividing by  $(\Delta x)$ :

$$\phi_1' = \frac{(\phi_1 - \phi_{i-1})}{(\Delta x)} + \frac{(-\Delta x)}{2!} \phi_1'' - \frac{(\Delta x)^2}{3!} \phi_1''' + \frac{(-\Delta x)^3}{4!} \phi_1^{IV} + \dots + (3.2)$$

These are the only known points according to our figure

These terms are eliminated from the expression. They are known as the error of the approximation

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## Backward Approximation First Derivative ( $\phi_1'$ ), continued

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**Numerical Differentiation**

- Overview
- Discretization of a function
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**Numerical Integration**

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**Lab Practice**

- Use of Excel
- Use of Matlab

- Therefore, the final approximation for the first derivative using two backward points is given by:

$$\phi_1' = \frac{(\phi_1 - \phi_{i-1})}{(\Delta x)} \quad (3.3)$$

- The error of the approximation is given by the truncated points from the series:

$$E(\phi_1') = \frac{(-\Delta x)}{2!} \phi_1'' - \frac{(\Delta x)^2}{3!} \phi_1''' + \frac{(-\Delta x)^3}{4!} \phi_1^{IV} + \dots + (3.4)$$

Largest term  $\uparrow$

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<b>Numerical Differentiation</b> - Overview - Discretization of a function - Examples <b>Numerical Integration</b> - Overview - Trapezoidal rule - 1/3 Simpson's rule <b>Lab Practice</b> - Use of Excel - Use of Matlab	<h3>Backward Approximation</h3> <h4>First Derivative (<math>\phi_i'</math>), continued</h4> <hr/>
	<ul style="list-style-type: none"> <li>The first term in the error equation is known as the order of the approximation (O). Therefore, we can say that the two point backward approximation has an order: <math>O(\Delta x)</math></li> <li>Notice that <math>0 &lt; \Delta x &lt; 1</math></li> <li>The smaller <math>\Delta x</math>, the smaller the error (Eq. 3.4), therefore, the more accurate the computation of the numerical derivative (Eq. 3.3)</li> </ul> <p style="text-align: center;">ChE 400      9/6/2006      10</p>

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<b>Numerical Differentiation</b> - Overview - Discretization of a function - Examples <b>Numerical Integration</b> - Overview - Trapezoidal rule - 1/3 Simpson's rule <b>Lab Practice</b> - Use of Excel - Use of Matlab	<h3>Procedure to Develop Numerical Approximations for the derivative</h3> <hr/>
	<ol style="list-style-type: none"> <li>Draw schematic with the discretized points involve in the calculation</li> <li>Use Taylor's series expansions for the points involved in the calculation (See Eqs. 1 to 4)</li> <li>Combine Eqs. 1-4 to obtain the required expression</li> <li>Simplify the obtain expression</li> <li>Truncate the equation containing only the known points</li> <li>Define the error and the order of the approximation</li> </ol> <p style="text-align: center;">ChE 400      9/6/2006      11</p>

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<h3>Example 1</h3> <hr/>
<ul style="list-style-type: none"> <li>Develop the backward approximation for the second derivative</li> </ul> <p style="text-align: center;">ChE 400      9/6/2006      12</p>

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## Example 2

- Develop the approximation for the first derivative using central points in the computation

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**Table I: Summary of Useful Approximations**

Approximation	Equation	Error (order of approximation)	Eqs. used in derivation
Backward	$\phi'_i = \frac{d\phi_i}{dx} = \frac{(\phi_i - \phi_{i-1})}{(\Delta x)}$	$O(\Delta x)$	Eq. (3)
	$\phi''_i = \frac{d^2\phi_i}{dx^2} = \frac{(\phi_i - 2\phi_{i-1} + \phi_{i-2})}{(\Delta x)^2}$	$O(\Delta x)$	Eqs. (3) & (4)
Forward	$\phi'_i = \frac{d\phi_i}{dx} = \frac{(\phi_{i+1} - \phi_i)}{(\Delta x)}$	$O(\Delta x)$	Eq. (1)
	$\phi''_i = \frac{d^2\phi_i}{dx^2} = \frac{(\phi_{i+2} - 2\phi_{i+1} + \phi_i)}{(\Delta x)^2}$	$O(\Delta x)$	Eqs. (2) & (1)
Central	$\phi'_i = \frac{d\phi_i}{dx} = \frac{(\phi_{i+1} - \phi_{i-1})}{2(\Delta x)}$	$O(\Delta x^2)$	Eqs. (1) & (3)
	$\phi''_i = \frac{d^2\phi_i}{dx^2} = \frac{(\phi_{i+1} - 2\phi_i + \phi_{i-1})}{(\Delta x)^2}$	$O(\Delta x^2)$	Eqs. (1) & (3)

Equations valid for equal segments, that is,  $\Delta x$  is constant.

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**Table I: Summary of Useful Approximations (continued)**

Approximation	Equation	Error (order of approximation)	Eqs. used in derivation
Backward (three points)	$\phi'_i = \frac{d\phi_i}{dx} = \frac{(3\phi_i - 4\phi_{i-1} + \phi_{i-2})}{2\Delta x}$	$O(\Delta x^2)$	Eqs. (3) & (4)
Forward (three points)	$\phi'_i = \frac{d\phi_i}{dx} = \frac{(4\phi_{i+1} - 3\phi_i - \phi_{i+2})}{2\Delta x}$	$O(\Delta x^2)$	Eqs. (2) & (1)

Equations valid for equal segments, that is,  $\Delta x$  is constant.

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<b>Numerical Differentiation</b> - Overview - Discretization of a function - Examples <b>Numerical Integration</b> - Overview - Trapezoidal rule - 1/3 Simpson's rule <b>Lab Practice</b> - Use of Excel - Use of Matlab	<h2>Procedure to Calculate Numerical Derivatives</h2> <hr/>
	<ol style="list-style-type: none"> <li>1. Draw schematic with the discretized points involve in the calculation, around the "i" value that your are interested in evaluating</li> <li>2. Use the appropriate equation from the ones given in Table I for the calculation of the derivative</li> <li>3. Calculate the derivative</li> </ol> <div style="border: 1px solid black; padding: 2px; margin-top: 5px;"> <p>Need to use this procedure all the time, for homework, exams, etc (<b>all the steps</b>)</p> </div>

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<b>Numerical Differentiation</b> - Overview - Discretization of a function - Examples <b>Numerical Integration</b> - Overview - Trapezoidal rule - 1/3 Simpson's rule <b>Lab Practice</b> - Use of Excel - Use of Matlab	<h2>Remarks</h2> <hr/>
	<ul style="list-style-type: none"> <li>• First order approximations usually good for functions that have a flat profile</li> <li>• Second order approximations usually good for functions that have a steep profile</li> <li>• The trend is to use high order approximations with small number of nodes. This approach saves time but <u>may provide the wrong answer</u></li> </ul>

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<h2>Example 3</h2> <hr/>
<ul style="list-style-type: none"> <li>• Calculate the first derivative of the given function <math>f(x) = x^2 + 3x - 2</math> at <math>x = 1</math>, using:             <ul style="list-style-type: none"> <li>- Backward approximation</li> <li>- Forward approximation</li> <li>- Central approximation</li> <li>- Compare your results with the analytical solution</li> </ul> </li> </ul>

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## Example 4

- The following data were collected when a large oil tanker was loading:

t, min	0	15	30	45	60	90	120
V, 10 <sup>6</sup> barrels	0.5	0.65	0.73	0.88	1.03	1.14	1.30

- Calculate the flow rate Q for each time to the order  $E=O(\Delta t^2)$

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## Numerical Integration

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- Lab Practice
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  - Use of Matlab

- Suppose that we have to integrate the function  $F(x)$ :

$$I = \int_{x_0}^{x_2} F(x) dx$$

- The idea of numerical methods of integration is to substitute the function  $F(x)$  by an equivalent function "y(x)", that is easier to integrate. Usually y(x) is a polynomial

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## Overview

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- Therefore:

$$I = \int_{x_0}^{x_2} F(x) dx \approx \int_{x_0}^{x_2} y(x) dx$$

- Methods to approximate function:
  - Newton-cotes methods
    - Equally spaced points
    - Modified for unequal spaced points
  - Gauss quadrature (unequally spaced points)

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## Newton-cotes methods

- Using Gregory-Newton Interpolation formula, the function is discretized into several segments of width "h", between the desired interval  $[x_0, x_n]$ , as shown:

Figure 2

Numerical Differentiation

- Overview
- Discretization of a function
- Examples

**Numerical Integration**

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- Trapezoidal rule
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Lab Practice

- Use of Excel
- Use of Matlab

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## Gregory-Newton interpolation

- Then, the function can be expressed as a product of polynomials:

$$y = y_0 + \frac{(x-x_0)}{h} \Delta y_0 + \frac{(x-x_0)(x-x_1)}{2!h^2} \Delta^2 y_0 + \frac{(x-x_0)(x-x_1)(x-x_2)}{3!h^3} \Delta^3 y_0 + \dots +$$

Eq. (5)

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Lab Practice

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## Trapezoidal Rule

- Using the first two terms of Eq. (5)

Figure 3

$$I_1 = \int_{x_0}^{x_1} \left[ y_0 + \frac{(x-x_0)}{h} \Delta y_0 \right] dx + \int_{x_0}^{x_1} R_n(x) dx$$

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Lab Practice

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Eq. (6)      ChE 400      9/6/2006      Error      24

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Numerical Differentiation - Overview - Discretization of a function - Examples <b>Numerical Integration</b> - Overview - Trapezoidal rule - 1/3 Simpson's rule Lab Practice - Use of Excel - Use of Matlab	<h2>Trapezoidal rule (continued)</h2> <hr/> <p>Integrating Eq. (6) and separating the error:</p> $I_1 \approx \frac{(y_0 + y_1)}{2} h \quad \text{Eq. (7)}$ $\text{Error} \approx \left[ -\frac{1}{12} h^3 y_0'' + \frac{h^4}{24} y_0'''' + \dots \right] \Rightarrow \text{Error} \approx O(h^3)$ <p style="text-align: right;">Eq. (8)</p> <p style="text-align: center;">ChE 400      9/6/2006      25</p>
	<hr/> <hr/> <hr/> <hr/> <hr/> <hr/> <hr/> <hr/> <hr/> <hr/> <hr/> <hr/>

Numerical Differentiation - Overview - Discretization of a function - Examples <b>Numerical Integration</b> - Overview - Trapezoidal rule - 1/3 Simpson's rule Lab Practice - Use of Excel - Use of Matlab	<h2>Trapezoidal rule (continued)</h2> <hr/> <ul style="list-style-type: none"> <li>Generalizing Eq. (7) for any trapezoid in the curve (see Figure 3):</li> </ul> $I_i \approx \frac{(y_{i-1} + y_i)}{2} h \quad \text{Eq. (9)}$ <ul style="list-style-type: none"> <li>Finally the total integral is obtained by adding each of the trapezoids shown in Figure 3:</li> </ul> $I \approx \sum_{i=1}^n I_i = I_1 + I_2 + I_3 + \dots + I_n \quad \text{Eq. (10)}$ <ul style="list-style-type: none"> <li>The error of the total integral is Error=O(h<sup>2</sup>)</li> </ul> <p style="text-align: center;">ChE 400      9/6/2006      26</p>
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Numerical Differentiation - Overview - Discretization of a function - Examples <b>Numerical Integration</b> - Overview - Trapezoidal rule - 1/3 Simpson's rule Lab Practice - Use of Excel - Use of Matlab	<h2>Trapezoidal Rule Procedure Constant "h"</h2> <hr/> <ol style="list-style-type: none"> <li>Draw schematic with the discretized points involved in the calculation (showing the trapezoids):           <ol style="list-style-type: none"> <li>Indicate the integrating range <math>[x_0, x_n]</math> and the value of "h". <math>h = (x_n - x_0)/n</math> where "n" is number of trapezoids</li> <li>Use as many trapezoids as possible (small "h"), this will make your calculation more accurate</li> </ol> </li> <li>Calculate the area of each trapezoid (I<sub>i</sub>) using Eq. 9</li> <li>Calculate the value of the Integral (I) by adding the area of the different trapezoids using Eq. (10)           <ol style="list-style-type: none"> <li>Sometimes programmers use the direct formula:</li> </ol> <math display="block">I \approx \frac{h}{2} \left[ y_0 + y_n + 2 \sum_{i=1}^{n-1} y_i \right]</math> </li> <li>Recommendation: It is ideal to perform these calculations using a table format. In the future (real work), it will be most likely that you will be solving numerical integrals by using an Excel spreadsheet that you write with the equations given in this procedure</li> </ol> <p style="text-align: center;">ChE 400      9/6/2006      27</p>
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## Example 5

- Solve the integral given below using trapezoidal rule. Compare your solution with the analytical solution.

$$I = \int_0^{0.8} F(x) dx$$

$$F(x) = 0.2 + 25x - 200x^2 + 675x^3 - 900x^4 + 400x^5$$

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## Trapezoidal Rule variable "h"

- Numerical Differentiation
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- You will encounter a variable h most of the time in your calculations, especially when you are using experimental data.
- The procedure is very similar to the one described for constant "h", except that you will have to calculate a new "h" all the time

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## Trapezoidal Rule Procedure Variable "h"

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1. Draw schematic with the discretized points involved in the calculation (showing the trapezoids):
  1. Indicate the integrating range  $[x_0, x_n]$
  2. Use as many trapezoids as possible (small "h"), this will make your calculation more accurate
2. Calculate the area of each trapezoid:
  1. Calculate your "h" for each trapezoid:  $h_i = (x_i - x_{i-1})$
  2. Calculate "I<sub>i</sub>" using Eq. 9
3. Calculate the value of the Integral (I) by adding the area of the different trapezoids using Eq. (10)
4. Recommendation: It is ideal to perform these calculations using a table format. In the future (real work), it will be most likely that you will be solving numerical integrals by using an Excel spreadsheet that you write with the equations given in this procedure

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## Example 6

- Solve the exercise given in example 5 using unequal segments for the trapezoidal rule

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## Simpson's 1/3 Rule

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– Use of Matlab

- Uses the first three terms of Gauss-Newton Interpolation (Eq. 5)
- It uses two segments of width  $h$ , therefore, integration is done faster
- It only works with an even number of segments (e.g.,  $n=2, 4, 6, 8, \dots$ , etc)
- Only applies for equal segments of  $h$

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## Simpson's 1/3 Rule continued

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- The area of each two segments is calculated by:

$$I_{2i} \approx \frac{h}{3} (y_{2[i-1]} + 4y_{2i-1} + y_{2i}) \quad \text{Eq. (11)}$$

- The total integral is calculated by:

$$I \approx \sum_{i=1}^{n/2} I_{2i} = I_2 + I_4 + I_6 + \dots + I_n \quad \text{Eq. (12)}$$

Where "n" is an even number

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Numerical Differentiation - Overview - Discretization of a function - Examples <b>Numerical Integration</b> - Overview - Trapezoidal rule - 1/3 Simpson's rule Lab Practice - Use of Excel - Use of Matlab	<h2>Simpson's 1/3 Rule continued</h2> <hr/>
	<ul style="list-style-type: none"> <li>The error is order: Error <math>O(h^4)</math>. More accurate than trapezoidal rule</li> <li>Programmers can also use the following expression to calculate the total integral:</li> </ul> $I \approx \frac{h}{3} \left( y_0 + y_n + 4 \sum_{i=1}^{n/2} y_{2i-1} + 2 \sum_{i=1}^{n/2-1} y_{2i} \right) \text{ Eq. (13)}$ <p style="text-align: center;">ChE 400      9/6/2006      34</p>

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Numerical Differentiation - Overview - Discretization of a function - Examples <b>Numerical Integration</b> - Overview - Trapezoidal rule - 1/3 Simpson's rule Lab Practice - Use of Excel - Use of Matlab	<h2>Simpson's 1/3 Rule Procedure</h2> <hr/>
	<ol style="list-style-type: none"> <li>Draw schematic with the segment points involved in the calculation (showing the individual areas):             <ol style="list-style-type: none"> <li>Divide your curve in "n" even number of segments</li> <li>Indicate the integrating range <math>[x_0, x_n]</math> and the value of "h". <math>h = (x_n - x_0)/n</math> where "n" is number of segments</li> <li>Use as many segments as possible (small "h"), this will make your calculation more accurate</li> </ol> </li> <li>Calculate the area of each two segments (<math>I_2</math>) using Eq. (11)</li> <li>Calculate the value of the Integral (I) by adding the area of the different segments using Eq. (12)</li> <li>Recommendation: It is ideal to perform these calculations using a table format. In the future (real work), it will be most likely that you will be solving numerical integrals by using an Excel spreadsheet that you write with the equations given in this procedure</li> </ol> <p style="text-align: center;">ChE 400      9/6/2006      35</p>

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<h2>Example 7</h2> <hr/>
<ul style="list-style-type: none"> <li>Solve the integral given below using Simpson's 1/3 rule (with 4 segments). Compare your solution with the analytical solution.</li> </ul> $I = \int_0^{0.8} F(x) dx$ $F(x) = 0.2 + 25x - 200x^2 + 675x^3 - 900x^4 + 400x^5$ <p style="text-align: center;">ChE 400      9/6/2006      36</p>

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Numerical Differentiation - Overview - Discretization of a function - Examples Numerical Integration - Overview - Trapezoidal rule - 1/3 Simpson's rule Lab Practice - Use of Excel - Use of Matlab	<h2>Use of Excel</h2> <hr/>
	<ul style="list-style-type: none"> <li>• The way to use excel to solve for numerical integrals is by developing a spreadsheet that will use the equations shown in this handout</li> <li>• It is not automatic. It is a very organized way to perform your calculation, instead of using a calculator</li> </ul> <p style="text-align: right;">ChE 400      9/6/2006      37</p>

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Numerical Differentiation - Overview - Discretization of a function - Examples Numerical Integration - Overview - Trapezoidal rule - 1/3 Simpson's rule Lab Practice - Use of Excel - Use of Matlab	<h2>Use of Matlab</h2> <hr/>
	<ul style="list-style-type: none"> <li>• Numerical integration using "quad" function</li> <li>• Symbolic integration using "int" function</li> </ul> <p style="text-align: right;">ChE 400      9/6/2006      38</p>

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<h2>Assignment</h2> <hr/>
<ul style="list-style-type: none"> <li>• Reproduce the results of all exercises in Tutorial 4</li> <li>• Solve Homework 5 (due 10/16/06), posted on web  <a href="http://www.ent.ohiou.edu/che/che400/Assignments.htm">http://www.ent.ohiou.edu/che/che400/Assignments.htm</a></li> <li>• Quiz 4, 10/16/06</li> </ul> <p style="text-align: right;">ChE 400      9/6/2006      39</p>

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## Summary

- Do all the exercises done in class by yourself
- Review and know all the methods given in this handout
- Reproduce by yourself all the exercises given in Tutorial 4
- Do by yourself the homework assignment
- Solve the proposed problems for the chapter

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